

M-410iB/140H



Max. load capacity
at wrist: 140 kg



Max. reach:
2850 mm

FANUC

Robot			Max. load capacity at wrist (kg)	Reach (mm)	Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						Moments (N-m)/Inertia (kg-m ²)			Protection		
Series	Version	Type						J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia	Average Power consumption (kW)	Body standard/optional	Wrist & J3 arm standard/optional
M-410	iB	140H	140	2850	5	± 0.05*	1200	360	155	112	20**	720	-	140	115	135	135	420	-	147	53	-	3	IP54	IP54

● standard ○ on request - not available * Based on ISO9283 **J4 can travel +/- 10 degrees away from the horizontal plane (the horizontal plane is where the faceplate points straight downwards)

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5-axis



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